

## Lebesgue Decomposition

$(X, \mathcal{A}, \lambda)$  measure space

$\mathbb{R}$   $\mathcal{B}(\mathbb{R})$  (Lebesgue measure) ( $\lambda([a,b]) = b-a$ )

Another measure  $\mu: \mathcal{B}(\mathbb{R}) \rightarrow [0, \infty]$

Def: (a)  $\mu$  is called absolutely continuous

if  $\lambda(A) = 0 \Rightarrow \mu(A) = 0$

for all  $A \in \mathcal{B}(\mathbb{R})$ .  $\mu \ll \lambda$

(b)  $\mu$  is called singular (w.r.t.  $\lambda$ )

if there is  $N \in \mathcal{B}(\mathbb{R})$  with  $\lambda(N) = 0$

and  $\mu(N^c) = 0$   $\mu \perp \lambda$ .

Example:  $\delta_0$  Dirac measure ( $\delta_0(\{x_0\}) = 1$ )

$N = \{x_0\}$ ,  $N^c = \mathbb{R} \setminus \{x_0\}$ .  $\lambda(N) = 0$ .

$\delta_0(\mathbb{R} \setminus \{x_0\}) = 0$ .  $\delta_0 \perp \lambda$

## Theorem (Decomposition by Lebesgue)

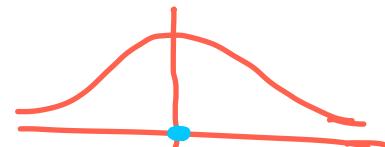
$\mu, \gamma$  prob. measures on  $(\Omega, \mathcal{A})$ . Then there exists a unique decomposition

$$\gamma = \gamma_{ac} + \gamma_s \text{ such that}$$

$$\gamma_{ac} \ll \mu \text{ and } \gamma_s \perp \mu.$$

Example:  $\gamma = \frac{1}{2} (N(0,1), \delta_0)$

$$\gamma = \gamma_{ac} + \gamma_s$$



$$\text{where } \gamma_{ac} = \frac{1}{2} N(0,1), \quad \gamma_s = \frac{1}{2} \delta_0$$

Cantor distribution: non-trivial distribution that is singular w.r.t.  $\lambda$ .

Construct the Cantor set:

- Start with  $C_0 := [0, 1]$

"remove middle part"



- $C_1 := [0, 1/3] \cup [2/3, 1]$

"remove middle part from all intervals"



$$\cdot C_2 :=$$

⋮

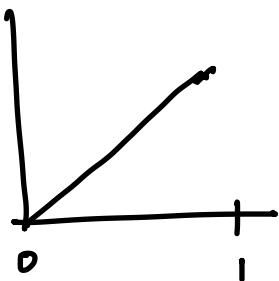


The Cantor set is the limit in this process.

Now construct a prob. distribution:

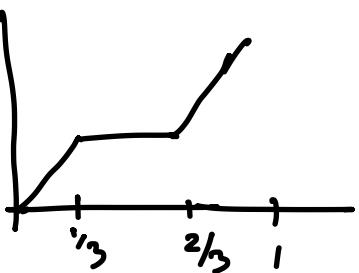
Consider the CDFs of the sets  $C_0, C_1, C_2 \dots$

$C_0 :$



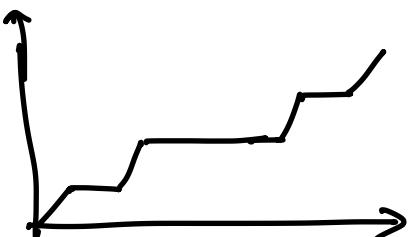
uniform on  $[0, 1]$

$C_1 :$



uniform on  
 $\{0, \frac{1}{3}\} \cup \{\frac{2}{3}, 1\}$

$C_2 :$



⋮

Take limit  $\xrightarrow{T}$ . Can prove many interesting properties:

- Cantor set is compact, non-empty, empty interior.  
only boundary points.

- The cdf of  $T$  is continuous.  $T$  is a prob. measure.

- But:  $\lambda(c) = 0$

$$\Rightarrow \lambda \perp T$$

## Cumulative Distribution Function

Let  $P$  be a probability measure on

$(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ . Define the function

$$F: \mathbb{R} \rightarrow \mathbb{R}, \quad x \mapsto P(-\infty, x])$$

We say that  $F$  is a cumulative distribution function (cdf), that satisfies the following properties:

(i)  $F$  is monotonically increasing,

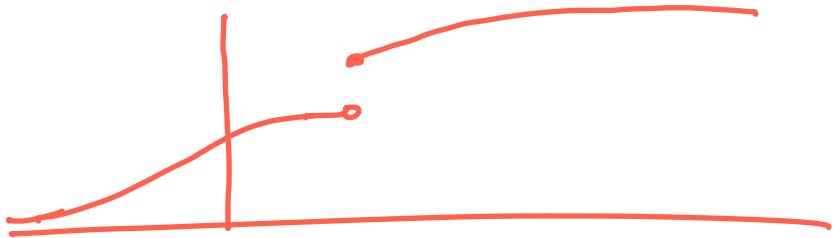
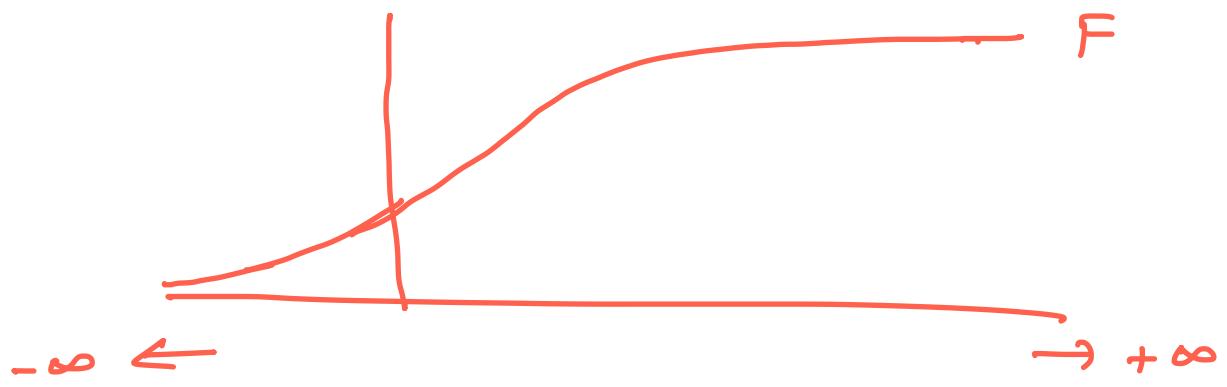
$$\lim_{x \rightarrow -\infty} F(x) = 0, \quad \lim_{x \rightarrow \infty} F(x) = 1$$

(ii)  $F$  is continuous from the right:

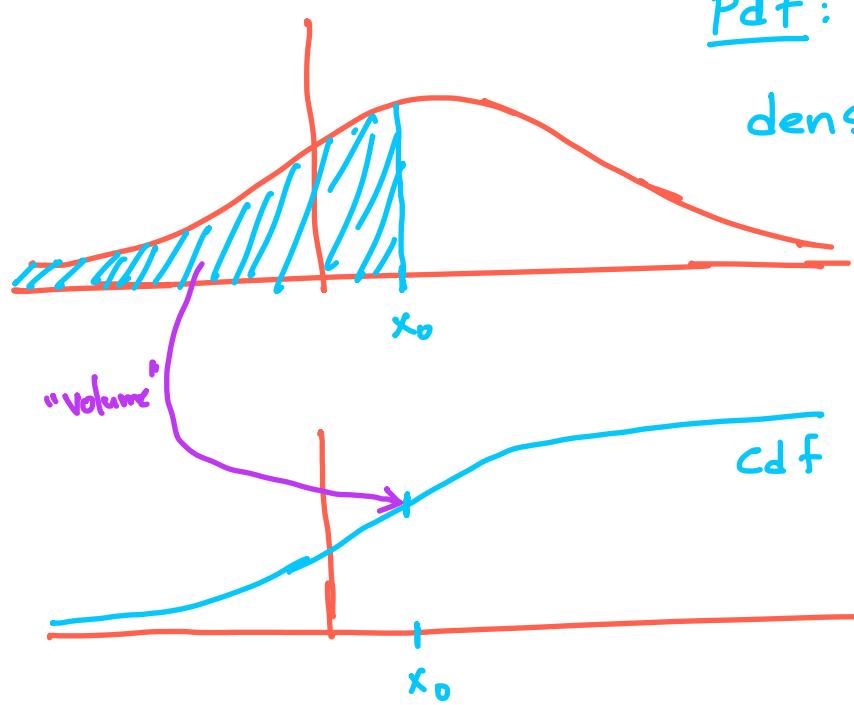
$(x_n)_{n \in \mathbb{N}}$  sequence with  $x_n \downarrow x$

(i.e.  $x_n \geq x_{n+1}$  and  $x_n \rightarrow x$ ) then also

$$F(x_n) \rightarrow F(x)$$



Pdf: prob. density func.  
density of normal dist.



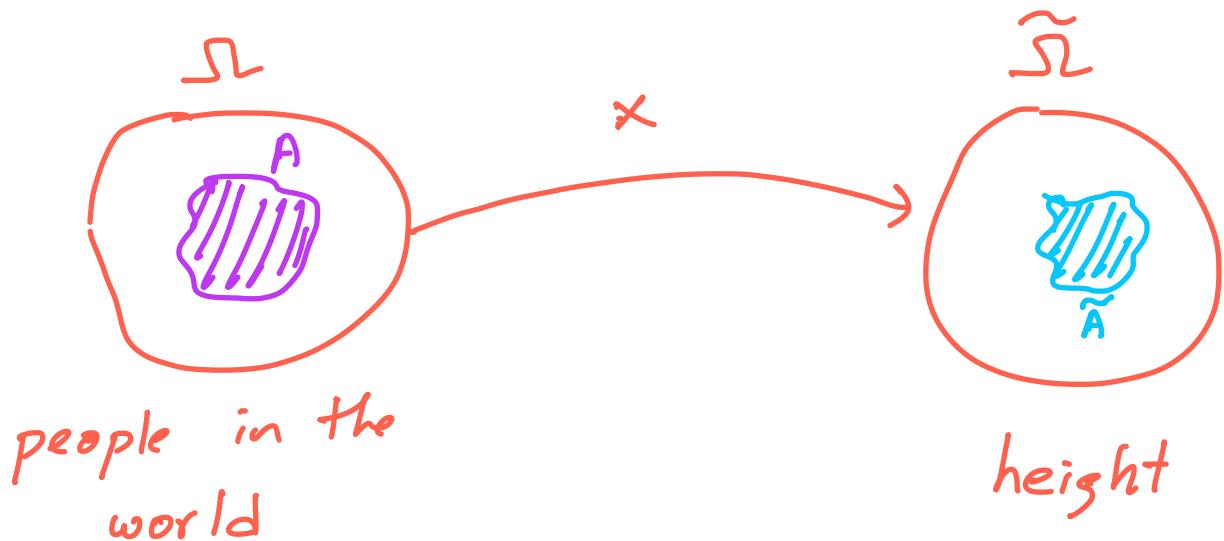
Let  $F: \mathbb{R} \rightarrow \mathbb{R}$  be a function with properties (i) and (ii). Then there exists a unique probability measure  $P$  on  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$  such that  $P((-\infty, x]) := F(x)$ .

Remark: We can go both ways. Given a PDF we construct CDF & given a CDF we can construct a unique PDF.

## Random Variable

Def: Let  $(\Omega, \mathcal{A}, P)$  be a probability space,  $(\tilde{\Omega}, \tilde{\mathcal{A}})$  be another measurable space. A mapping  $X: \Omega \rightarrow \tilde{\Omega}$  is called a random variable if  $X$  is measurable, i.e.

$$\forall \tilde{A} \in \tilde{\mathcal{A}}: X^{-1}(\tilde{A}) := \{ \omega \in \Omega \mid X(\omega) \in \tilde{A} \} \in \mathcal{A}.$$



$A =$  "people that are at least 6ft"

$\tilde{A} =$  "at least 6ft"

$$P(A) = 0.1$$

Example: sum of two dice.

$$\Omega = \{(i,j) \mid i,j \in \{1, 2, \dots, 6\}\}$$

$$A = P(\Omega)$$

$$\tilde{\Omega} = \{2, 3, \dots, 12\}$$

$$P(\{(i,j)\}) = \frac{1}{36}$$

$$\tilde{A} = P(\tilde{\Omega})$$

$\times$  "sum of the two dice"

$$X: \Omega \rightarrow \{2, 3, \dots, 12\}, (i,j) \mapsto i+j$$

Is measurable.

Def: A random variable  $X: \Omega \rightarrow \tilde{\Omega}$  induces a measure on the target space:

For  $\tilde{A} \in \tilde{A}$  we define

$$P_X(\tilde{A}) := P(X^{-1}\{\tilde{A}\})$$

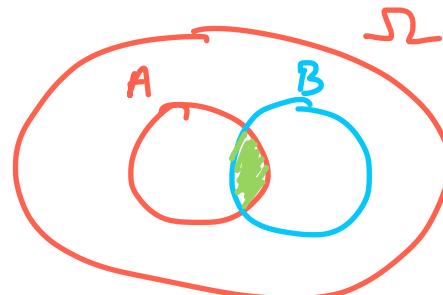
This is a probability measure on  $(\tilde{\Omega}, \tilde{A})$  and it is called the distribution of X.

Def:  $X: (\Omega, \mathcal{A}, P) \rightarrow (\tilde{\Omega}, \tilde{\mathcal{A}})$ . Then the family  $\sigma(X) := \{X^{-1}(\tilde{A}) \mid \tilde{A} \in \tilde{\mathcal{A}}\}$  is a  $\sigma$ -algebra on  $\Omega$  and it is called the  $\sigma$ -algebra induced by  $X$ .

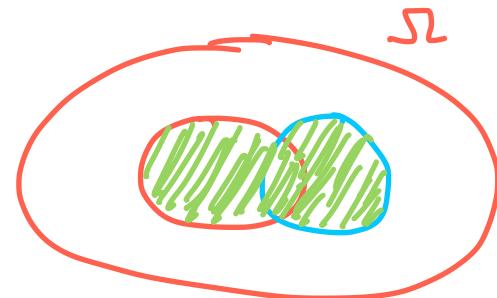
(if is the smallest  $\sigma$ -algebra on  $\Omega$   
that makes  $X$  measurable)

## Conditional Probabilities

Notation :  $P(A \cap B) = P(\text{"A and B"})$



$P(A \cup B) = P(\text{"A or B"})$



Def : Let  $(\Omega, \mathcal{A}, P)$  be a probability space.

$A, B \in \mathcal{A}$ ,  $P(B) > 0$ . Then

$P(A|B) := \frac{P(A \cap B)}{P(B)}$  is called

the conditional probability of  
A given B.

Theorem: The mapping  $P_B : \mathcal{A} \rightarrow [0, 1]$ ,  
 $A \mapsto P(A|B)$  is a probability measure  
on  $(\mathcal{S}_2, \mathcal{A})$ , it is called the conditional  
distribution of  $P$  with respect to  $B$ .

Examples: ① two dice

$$P(\text{"sum is 9"} | \text{"first die was 3"})$$

②  $\mathcal{S}_2 = \text{all persons on earth}$

$$A = P(\Omega)$$

$P = \text{"uniform"}$

Event  $A$ : "person has been vaccinated"

$B$ : "person has disease"

$$\left. \begin{cases} P(\text{disease} | \text{vaccinated}) \rightarrow \text{not vacc.} \\ P(\text{vaccinated} | \text{disease}) \end{cases} \right\} \text{all person}$$